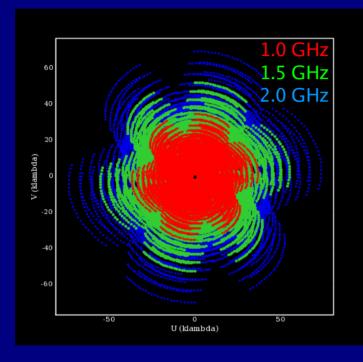
# Multi-Frequency Synthesis Imaging with Multi-Scale Deconvolution (EVLA, e-MERLIN)



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(Thesis advisor : T.J.Cornwell (ATNF))

Imaging and Calibration Algorithms for EVLA, e-MERLIN, ALMA

> Oxford, U.K. December 02, 2008

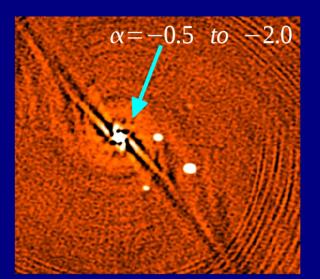
## Outline :

- Comparison of existing algorithms
- A simple extension of spectral-line imaging
- A multi-scale multi-frequency technique that generates spectral index and spectral curvature maps.
- Application to data taken with EVLA receivers and VLA correlator ( 1 2 GHz )
- Frequency-dependent primary-beam correction (preliminary results)

# MFS for point-source fields (currently used methods)

(U.Rau, T.J.Cornwell, EVLA Memo 101, 2006)

Standard Continuum Imaging Peak residual : 60 u Jy



Dyn range limit ~ 1000 for  $\alpha$  ~ -1.0 across 1-2 GHz (Conway et al, 1990)

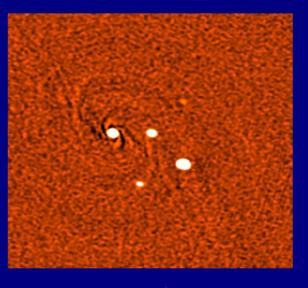
Simulation of 5 point sources : 100mJy, 10mJy, 1mJy, 100uJy, 10uJy

Spectral index of 10mJy source (800 MHz at 1.4 GHz) : -0.5 to -2.0

Target RMS : 1 u Jy

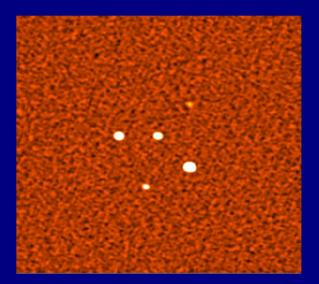
MF-CLEAN (Miriad)

Linear Fit to Spectrum Peak residual : 10 uJy



Both methods will work for ~ Point-sources.

Spectral-Line Imaging Peak residual : 2 uJy



Insufficient for extended sources and sources whose flux ~  $\sigma_{\rm chan}$ 

U.Rau (NRAO/NMT/ATNF)

# Hybrid Algorithm - on extended emission

(U.Rau, T.J.Cornwell, 2008 (in prep))

# Continuum Map after<br/>Spectral-Line ImagingContinuum residualContinuum residualCarget dynamic range : 10°<br/>Larget dynamic range : 10°<br/>Larget dynamic range : 10°<br/>Larget dynamic range : 10°<br/>Component image)Max Dynamic range : 10°<br/>Continuum residualsMax Dynamic range : 10°<br/>(component image)

Spectral-Line Imaging + Deconvolution on continuum residuals

Cygnus-A<sup>+</sup> simulation (40 channels, L-Band to C-Band, 4 hours ) => Ideal data

Simple hybrid algorithm can handle arbitrary spectra and will suffice (upto calibration limits)

- for point sources
- for extended sources if there is sufficient uv-coverage per channel

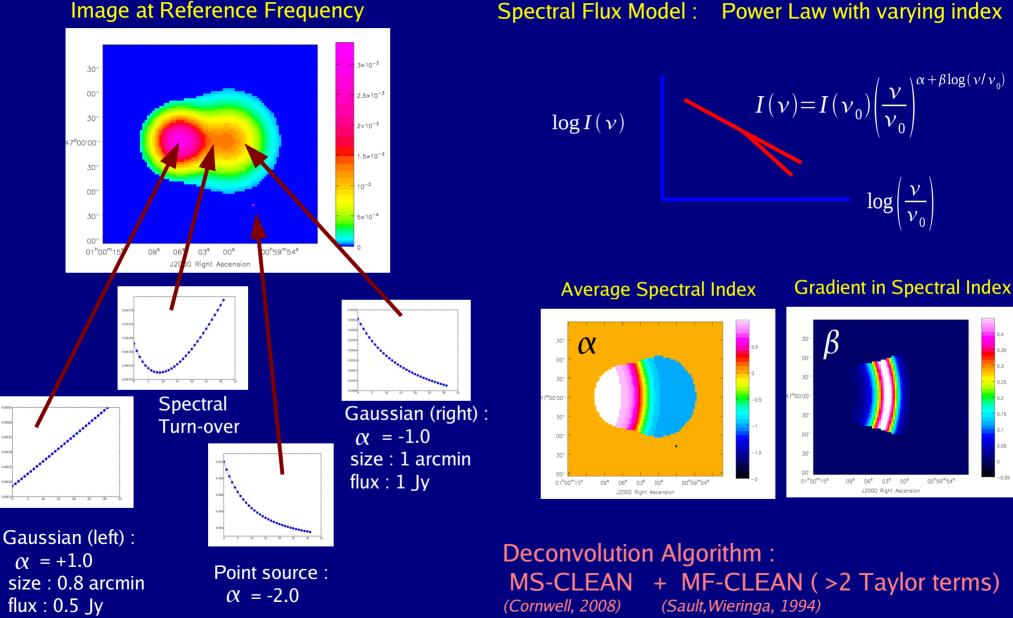
## Insufficient uv-coverage per channel

=> solve for total-intensity and spectrum simultaneously.

(MF-CLEAN and other parametric solvers)

# Multi-Scale Multi-Frequency-Synthesis (U.Rau, T.J.Cornwell, 2008 (in prep))

#### EVLA C-array simulation, 1-2 GHz Image at Reference Frequency



U.Rau (NRAO/NMT/ATNF)

Imaging and Calibration Algorithms for EVLA, e-MERLIN and ALMA, Oxford, 02 Dec 2008

4/12

Power Law with varying index

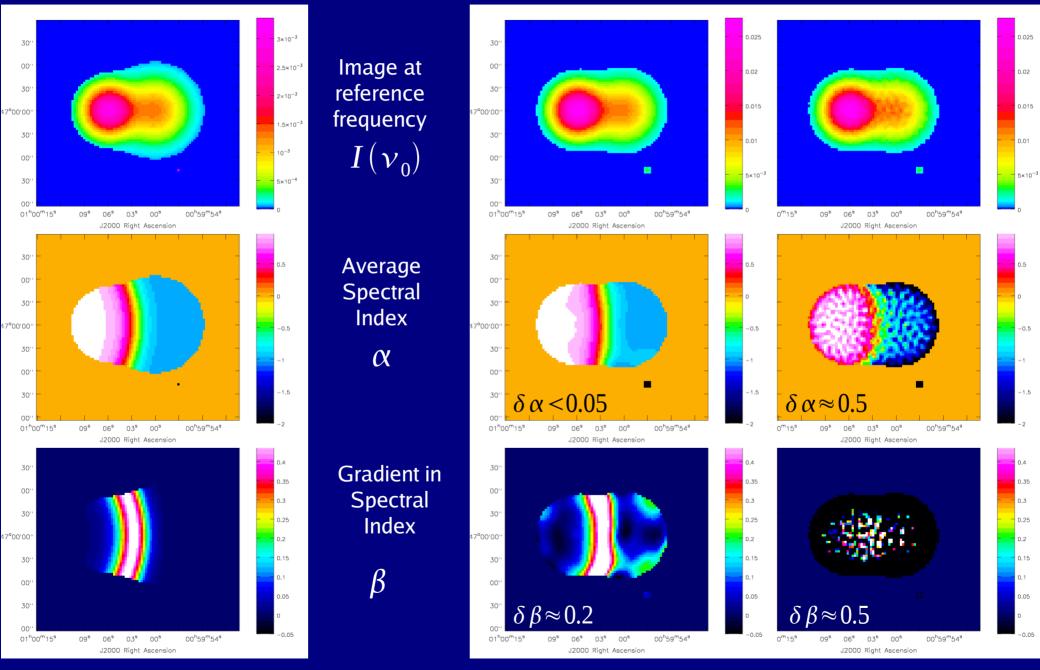
## **True Images**

## MS-MFS

(multi-scale source model)

## MF-Clean (3 Taylor terms)

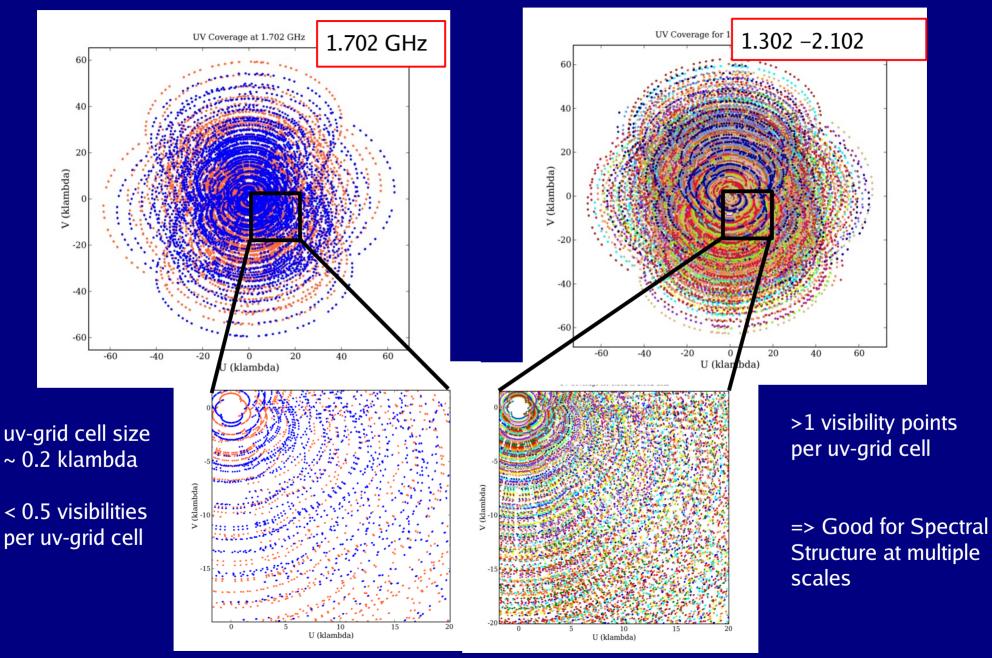
#### (point-source pixel model)



U.Rau (NRAO/NMT/ATNF)

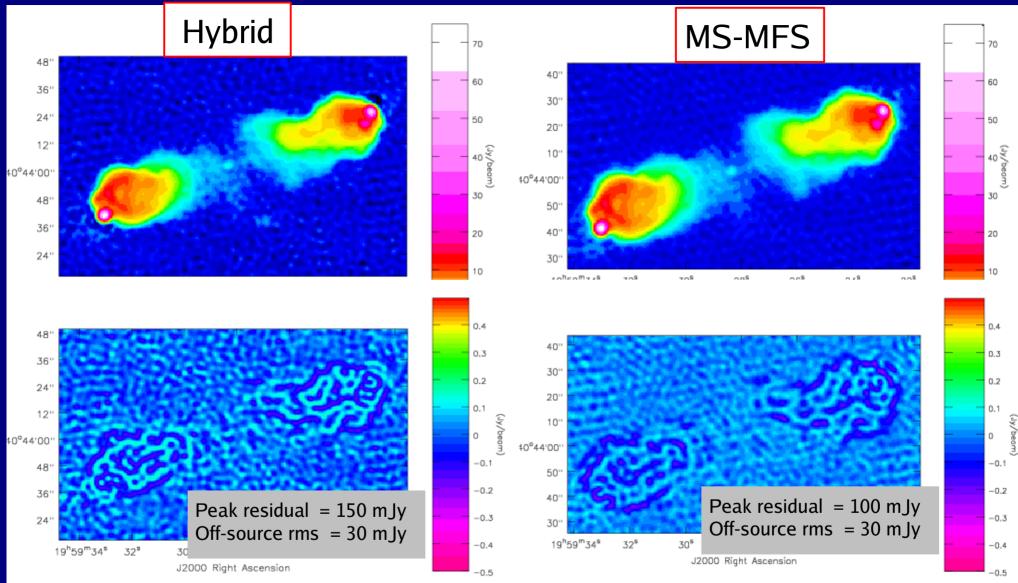
# Example synthesized wide-band EVLA uv-coverage

CygA : Cycle through 9 frequency bands, 20 one-minute snapshots per band, spread over 8 hours )



U.Rau (NRAO/NMT/ATNF)

## CygA – Continuum Image and Residuals

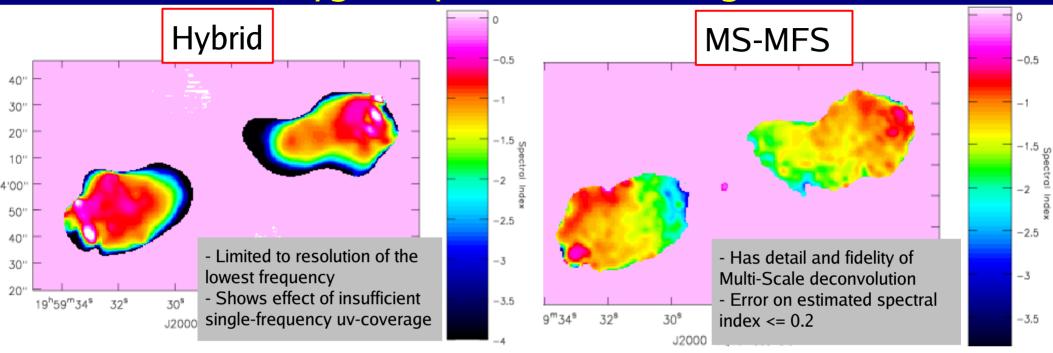


## => Similar results

- both algorithms work well
- both have few-sigma residual deconvolution errors.

U.Rau (NRAO/NMT/ATNF)

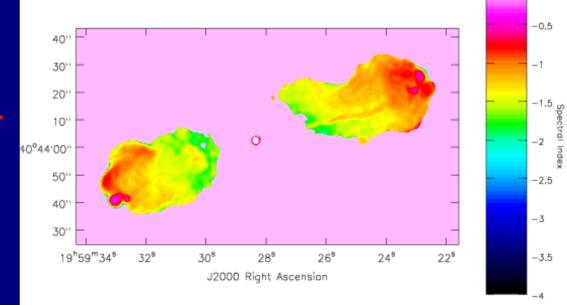
# **CygA - Spectral Index Images**



For comparison,

Spectral Index Map constructed from images at 1.4GHz and 4.8GHz, obtained from C.Carilli et al, Ap.J. 1991 (VLA A,B,C,D Array at L and C band)

Map has been smoothed to 1 arcsec.



Imaging and Calibration Algorith

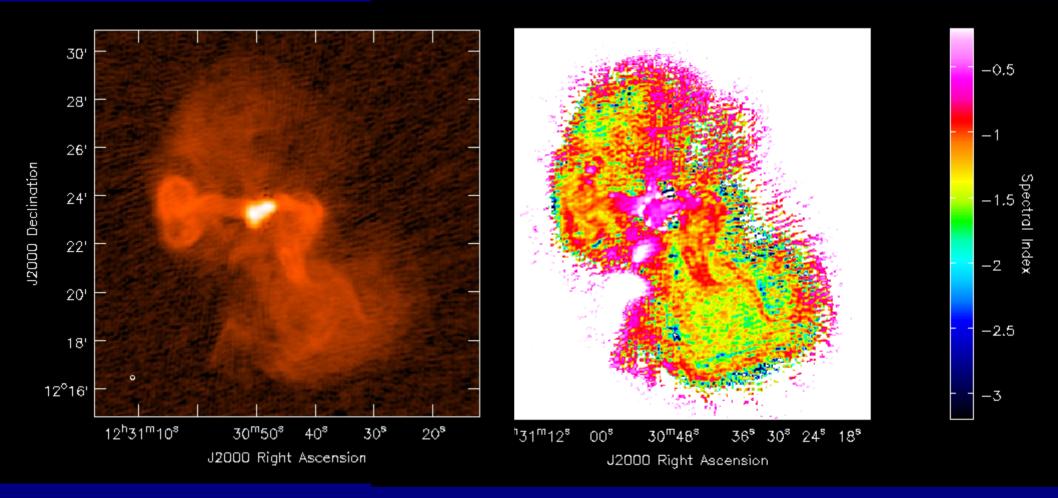
-0.5

ictral

-2.5

## M87 data + images (so far...)

VLA C-array : cycle through 16 frequencies between 1.18 –1.86 GHz, 25MHz bands, RR,LL ~ 30 mins per frequency, spread across 10 hrs => 10 x 3min \$napshots'per frequency



### **Total Intensity Image**

#### Spectral Index Map

U.Rau (NRAO/NMT/ATNF)

# M87 - Spectral Curvature

Points : from Spectral Line Images

Lines : from MS-MFS

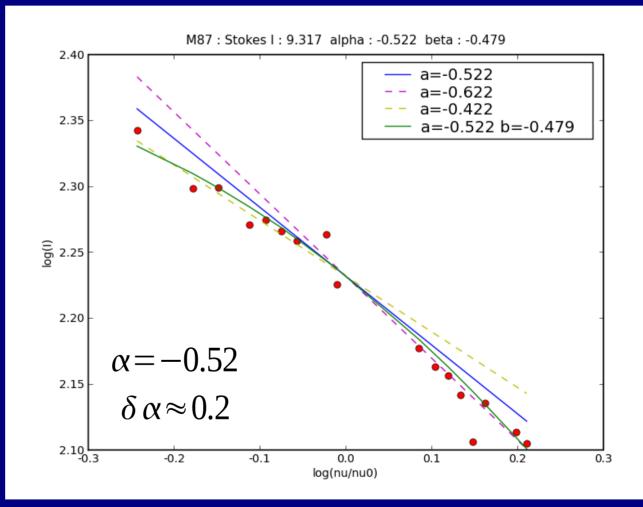
=> Need < 1% error in flux amplitude to fit this spectral curvature.

From a more general error analysis from fitting an exponential with a polynomial (1-2 GHz)

Need SNR > 6 to fit spectral index ~ 1.0

Need SNR > 100 to fit spectral index variation ~ 0.2

#### Spectrum of M87 core + inner jet region (1.18 GHz- 1.86 GHz)



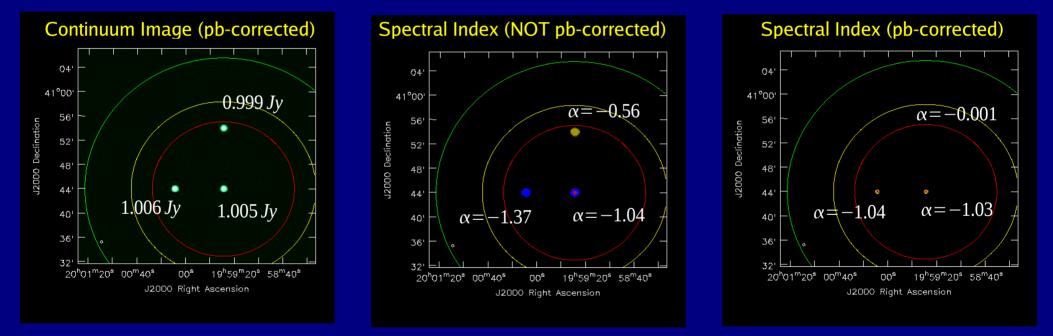
## Frequency-Dependent Primary-Beam correction

(U.Rau, T.J.Cornwell, 2008 (in prep))

## Preliminary results :

Correct the MS-MFS results by a model of the spectral variation of the primary beam.

Below : HPBW at 1.0 GHz (green) , 1.4 GHz (yellow) and 1.8 GHz (red) 3 point sources : 1 Jy each, Bottom 2 sources have  $\alpha = -1.0$ 



#### Work in progress : using CASA / ASKAPSOFT

- Test if this method is adequate for time-varying primary beams and pointing offsets.
- Apply frequency-dependant direction-dependent corrections via gridding convolution functions.

## Summary

Wide-Band receivers provide increased uv-coverage and sensitivity and measure spectra.

Hybrid :

- Requires adequate UV-coverage per channel
- Angular resolution of spectral index and curvature : lowest
- Easily parallelizable (Major and Minor cycles)

MS-MFS :

- Can handle sparse UV-coverage per channel (e-MERLIN!)
- Angular resolution of spectral index and curvature : highest
- Non-trivial to parallelize the Minor Cycle (Major cycle parallelized in ASKAPSOFT)

Spatial Structure :

- Fields of well-separated point-sources : Algorithms can get to 10<sup>6</sup> dynamic range
- Extended emission : Algorithms can get to  $>10^5$  dynamic range (limited by multiscale algorithms)

Spectral Structure :

- Can correct for the frequency dependent primary beam (limits yet to be understood)
- Error Analysis for a power law spectrum with varying index : (for 2:1 bandwidth) Need SNR > 6 to fit spectral index ~ 1.0 Need SNR > 50 to fit spectral index variation ~ 0.2